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equations for
viscoelastic fluids, and
equations in cylindrical
and spherical
coordinates.

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Lai et al, Introduction
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Mechanics From the
equation $(\text{div}T) \cdot a =$
 $\text{div}(T a) - \text{tr}(T \nabla a)$
[See Eq. 2.29.3)] verify
that in polar $\partial T_1 \partial T_{\theta\theta}$

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coordinates, the θ -component of the vector $(\text{div}T)$ is: $(\text{div}T)_\theta = \theta_r + \partial_r r \partial_\theta r$

-----Ans. $(\text{div}T) \cdot a = \text{div}(T a) - \text{tr}(T \nabla a) \rightarrow (\text{div}T) \cdot e_\theta = \text{div}(T e_\theta) - \text{tr}(T \nabla e_\theta)$ Now,
2.76

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form of the basic

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applications to

problems in elasticity,

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viscoelasticity. An

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mechanics is a theory

of the kinematics and

dynamics of material

bodies in the limit in

which matter can be

assumed to be

infinitely subdividable.

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upon which several
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